Mathematical Visualization Lectures Nov. 12th - Nov. 15th

Nov. 12th

Recall from last week: E(2) with O(2) the orthogonal group and $\mathbb{R}(2)$ the translation group $\phi: E(2) \to O(2)$ with $\begin{pmatrix} R & T \\ 0 & 1 \end{pmatrix} \to \begin{pmatrix} R & 0 \\ 0 & 1 \end{pmatrix}$ is a group homomorphism It is: $\ker(\phi) = \mathbb{R}(2)$, i.e. $\mathbb{R}(2) \leq E(2)$.

$$R_{0,\theta} \underbrace{v}_{0} \begin{array}{c} P \end{array} \stackrel{R_{P,\theta}}{\underset{0}{\overset{}}} R_{P,\theta} = T_{v} \circ R_{0,\theta} \circ T_{v}^{-1}$$

Remember that $h \mapsto ghg^{-1}$ is the conjugation by g. If you put in a translation it stays a translation. This is another way to see that the translation group is a normal subgroup.

Discrete subgroup: the identity element is isolated, i.e. it has a neighborhood with no other group element.



dim ker ϕ gives a classification of discrete subgroups Let $\Gamma \leq E(2)$ be a discrete subgroup. Then $\phi(\Gamma) \subset O(2)$ and define $T := \ker \phi(\Gamma) \subset \mathbb{R}(2)$ dim T = 0, 1, 2

0: point $(C_n \text{ or } D_n \text{ where } C_n \text{ is generated by a } \frac{2\pi}{n}$ rotation and D_n by two intersection reflections of angle $\frac{\pi}{n}$



- 1: frieze groups (there are seven of them)
- 2: wallpaper groups (or in general: crystallographic groups) there are 17 of them

Decision tree for patterns to recognize frieze groups



Question: Is there a cleaner set of questions? (there is, as we'll see tomorrow) Wallpaper groups: order: 2, 3, 4, 6, C_n or D_n orientation preserving? YES C_n , id, NO D_n Three groups with D_n (instance reflection); and it is

Three groups with D_1 (just one reflection): xx, **, *x

C_1	0	D_1	**, xx, *x
C_2	2222	D_2	*2222, 2 * 22, 22*, 22x
C_3	333	D_3	*3333, 3 * 3
C_4	244	D_4	4 * 2, *244
C_6	236	D_6	*236

Nov. 13th (Problem class)



every element of G can be written as: T or Tr

Then Charles explained what this means for Assignment 3.

Nov. 15th

Classification of compact surfaces



In higher dimensions, people distinguish topological, smooth and PL manifolds.

A theorem from the 1930's says there is no distinction in 2 or 3 dimensions.

For us, it means we can assume any compact surface is triangulated, i.e. it arises from glueing (finitely many) triangles together. Zip-proof:



Features in surfaces:

puncture: remove an open disk *handle*: remove two open disks, sew in a cylinder



cross-handle: remove two disks, sew in cylinder this way



cross-cap: remove a disk, sew in Möbius band



sphere with a puncture: disk sphere with two punctures: cylinder sphere with a handle: torus sphere with cross-handle: Klein-Bottle (K^2) sphere with a cross-cap: $\mathbb{R}P^2$ (projective plane) sphere with two cross-caps: K^2

sphere with a cross-cap. \mathbb{R}^{r} (projective plane) sphere with two cross-caps.

locally: adding two crosscaps = adding cross-handle

Temporary Definition:

An *ordinary* surface is a finite union of components, each being asphere with some number of punctures, handles, cross-handles, cross-caps added.

First goal: Every surface is ordinary. Follows immediately from:

Lemma:

If we start with an ordinary surface and zip up one zipper, the result is ordinary.

Proof:



Suppose first the two sides of the zipper are full boundary circles.



If the two sides of the zipper start on the same component, the zipping replaces two punctures by a handle or cross-handle.

If the zippers do not go all the way around, the result is the same, except with a puncture left. This is also the case if one is a full loop and the other only a half.



What if the two sides of the zipper are the same boundary components?



3



On a non-orientable component (i.e. one with at least one cross-cap or cross-handle) there is no difference between adding a handle or a cross-handle.



Final classification

Each connected compact surface is either a sphere with $g \ge 0$ handles and $k \ge 0$ punctures $\Sigma_{g,k}$ (if orientable) or if non-orientable is a sphere with $h \ge 1$ cross-caps and $k \ge 0$ punctures $N_{h,k}$. $\Sigma_{0,2}$ = cylinder, $N_{1,0} = \mathbb{R}P^2$, $N_{1,1}$ = Möbius band, $N_{2,0} = K^2$.

Euler characteristic



$$\begin{split} \chi(S^2) &= 2\\ \chi(\Sigma_{g,k}) &= 2 - 2g - k\\ \chi(N_{h,k}) &= 2 - h - k \end{split}$$

The type of a connected compact surface can be determined from:

k = # boundary components, χ , orientable?

If $\chi + k$ is odd, then the surface is non-orientable.